

#### An Approach for Monitoring and Smart Planning of Urban Solid Waste Management Using Smart-M3 Platform

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### Introduction

#### **Global Issue**



## Introduction

Characteristics of current waste collection systems:

The number of bins and the number of vehicles are generally <u>estimated</u> based on the number of citizens.

Effects:

- Or the provision of poor service
- Or to incur in high costs
- The collection of waste is typically fixed weekly but without taking into account the actual state of the level of fullness for each bin.

#### Effects:

- Or the collection of semi-empty bins
- Or the trash accumulations that cause degrading conditions of hygiene of the city.

### Introduction





Spread of low cost devices or objects having long battery life enables <u>monitoring</u> of bins' fullness





#### What is a SWM?

**On-site and in <u>real-time</u> monitoring** 



#### Data <u>elaboration</u> through decisional algorithms to apply different <u>strategies</u>

# Smart waste management

## What was done?

An approach to smart waste collection is proposed able to <u>improve</u> and <u>optimize</u> the handling of solid urban waste.

Through: Monitoring + Data Elaboration & using Smart-M3 Platform



### **Hardware Architecture**



# Why Smart-M3 for SWM?

<u>Characteristics of SWM</u>: highly dynamic, fast data production, presence of many users that require this data, heterogeneous devices.

#### Smart-M3 allows:

- high level of <u>decoupling</u> between producer and consumer of data => unawareness of all participants;
- sharing of knowledge and access to <u>the freshest</u> data on the monitored environment <u>independent</u> of the operating system or manufacturer => through the use of ontology;
- an wide range of APIs and ease of implementation;
- good degree of ease <u>to extend</u> and <u>integrate</u> different <u>applications</u> in similar contexts;



#### 1 - Real-time monitoring for intelligent daily planning



**Control Center:** 

#### **Light Pole:**

- SensorsLightPole-KP updates sensor data within the smart space after operations of aggregation.
- CoordsLightPole-KP is responsible for updating the coordinates of the bins.

GarbageLevelManager-KP collects data from the various proximity sensors and save them for offline elaboration and time series analysis.



#### 1 - Real-time monitoring for intelligent daily planning



#### **Control Center:**

- GarbageLevelManager-KP sets status bins to: empty, halfempty, half-full or full.
- VehicleStatusManager-KP determines if an area must, may, or doesn't require the collection and set status of vehicles to work or not work.

Waste Vehicle: obtains command to work or not work and updates its coords.



#### 2 - Real-time monitoring and incentives for citizens

#### **User's Device:**

- LevelBinsForUser- KP notifies to users about the status of the closest bins to him according to filter options selected.
- User-KP makes an insert-query to add the access token to identify the user.

#### **Control Center:**

- The UsersManager-KP is notified when a user locks a bin.
- BinsWeightManager-KP measures the amount of trash thrown by the user and converts them in "green points".



# Ontology



# **Simulation and Application**



Simulation with 3 vehicles. Bins to collect in 3 different areas of a city.

User Application:

- (a) filter search query;
- (b) bins empty near the user for different waste types;
- (c) bin lock.



There are several future works and improvements:

- Modify the <u>users authentication</u> and <u>atomic lock</u> of bins during the collection of green-point in accordance with Smart-M3's features.
- Implement <u>graphical interfaces</u> for the control center and complete Android applications.
- Extend the system adding <u>other use cases</u> and applications for smart cities (ex. smart traffic monitoring).
- Study of <u>models</u> that offer the best results in terms of <u>decision-making</u> and <u>optimal route</u> for vehicles.

#### **Thanks For Your Attention!**



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