

# Random multiple access organization in telecommunication systems with large user population



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Russian Federation



# Session Agenda

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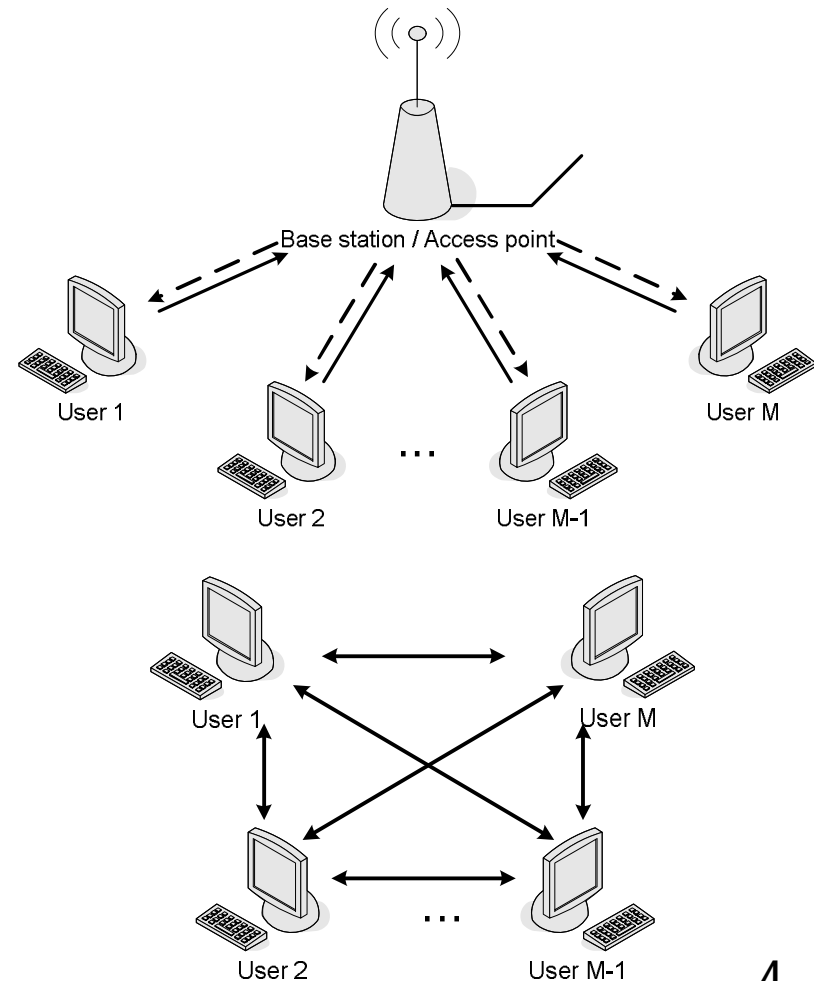
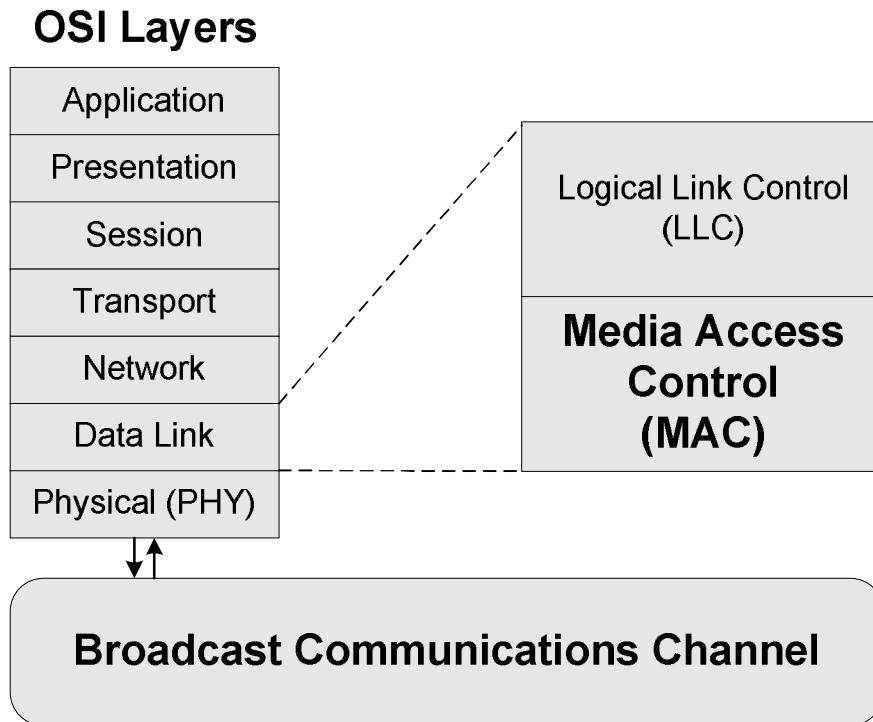
- n **Media access control** role for network communication
- n **Reference model** of a random multiple access (RMA) system
- n **Instability** of the RMA algorithms in the existing telecommunication systems
- n **Tree RMA algorithms** as a possible solution for the instability problem
- n **Tree algorithms implementation issues** and alternative proposals



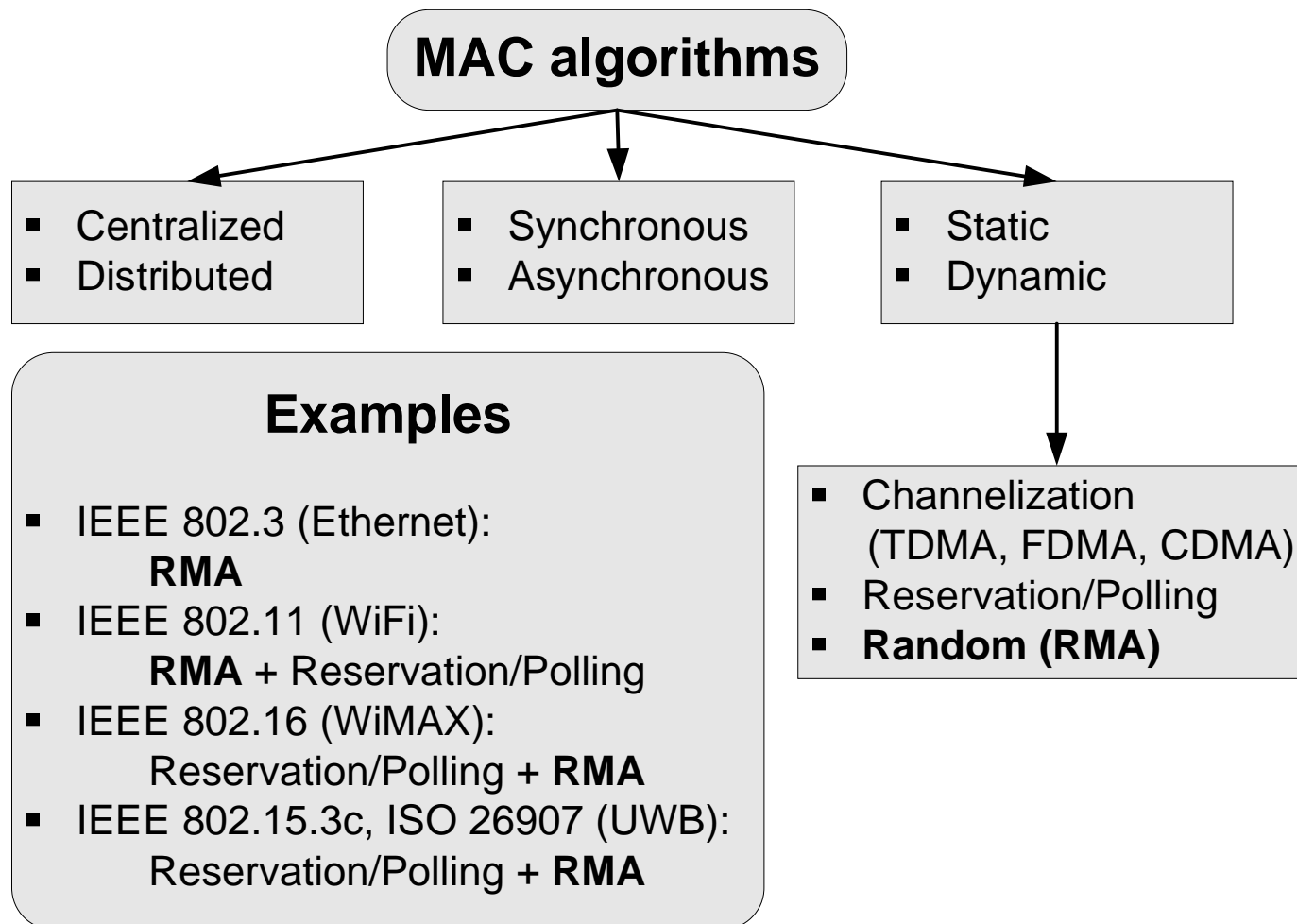
# Media access control role for network communication

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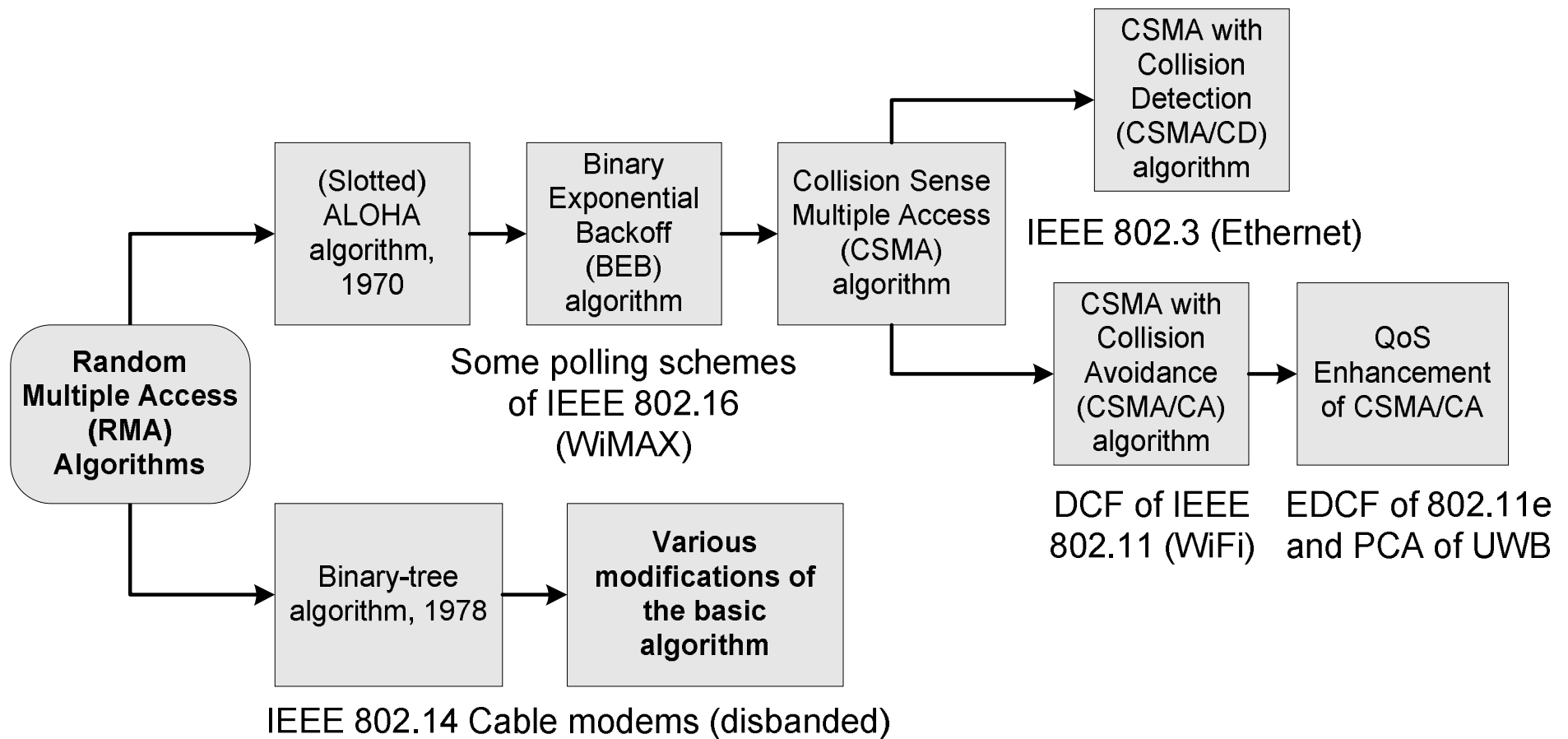
# Primary Research Focus



# MAC Algorithms Classification



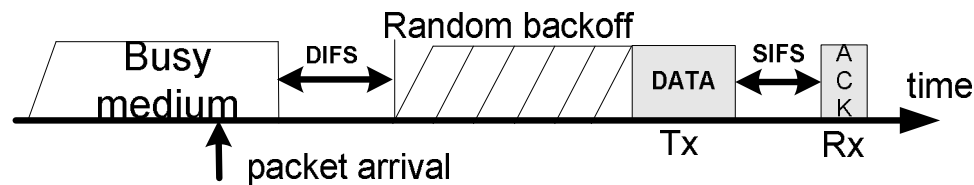
# RMA Algorithms Evolution



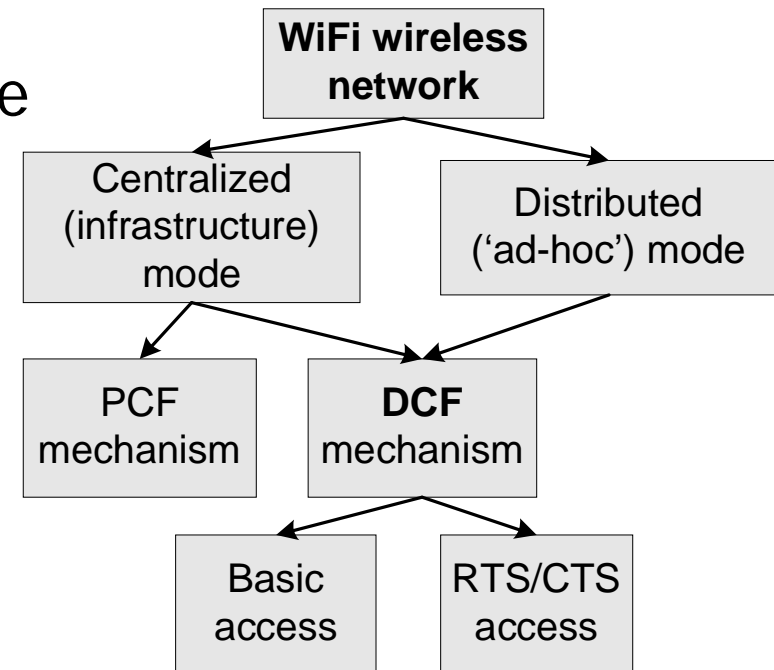
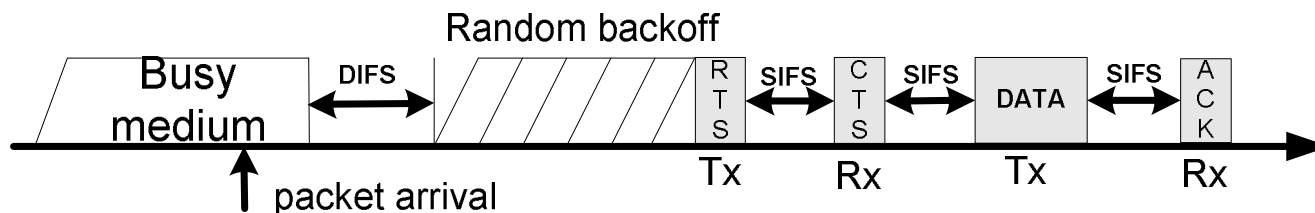
# RMA Applications: IEEE 802.11 LAN

Collision Sense Multiple Access with Collision Avoidance (CSMA/CA) scheme

Basic access snapshot

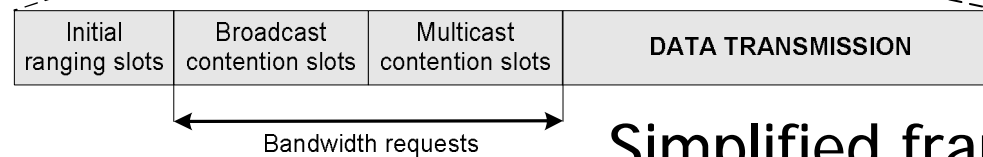
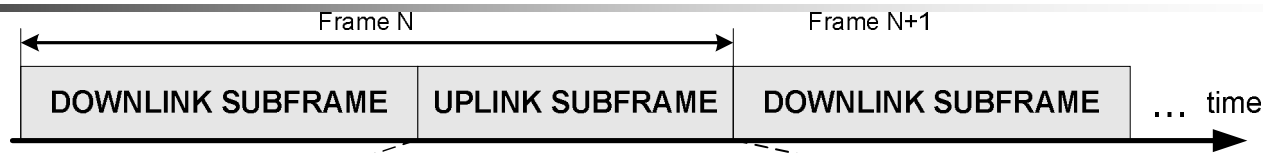


RTS/CTS access snapshot

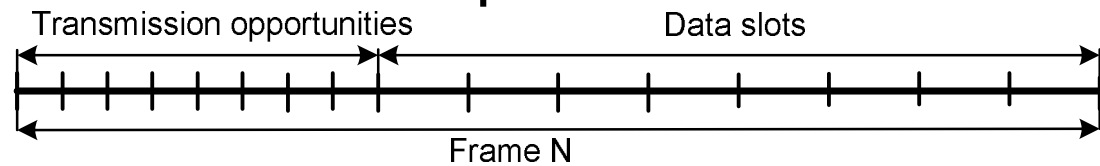


# RMA Applications: IEEE 802.16 WAN

General frame structure:



Simplified frame structure:



Polling schemes

- n Unicast (deterministic)
- n Multicast (for nrtPS, ertPS and BE connections only)
- n Broadcast

Collision resolution

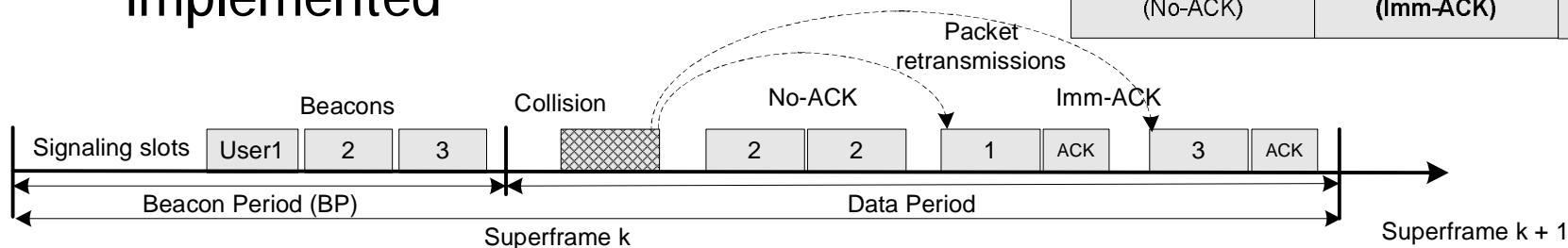
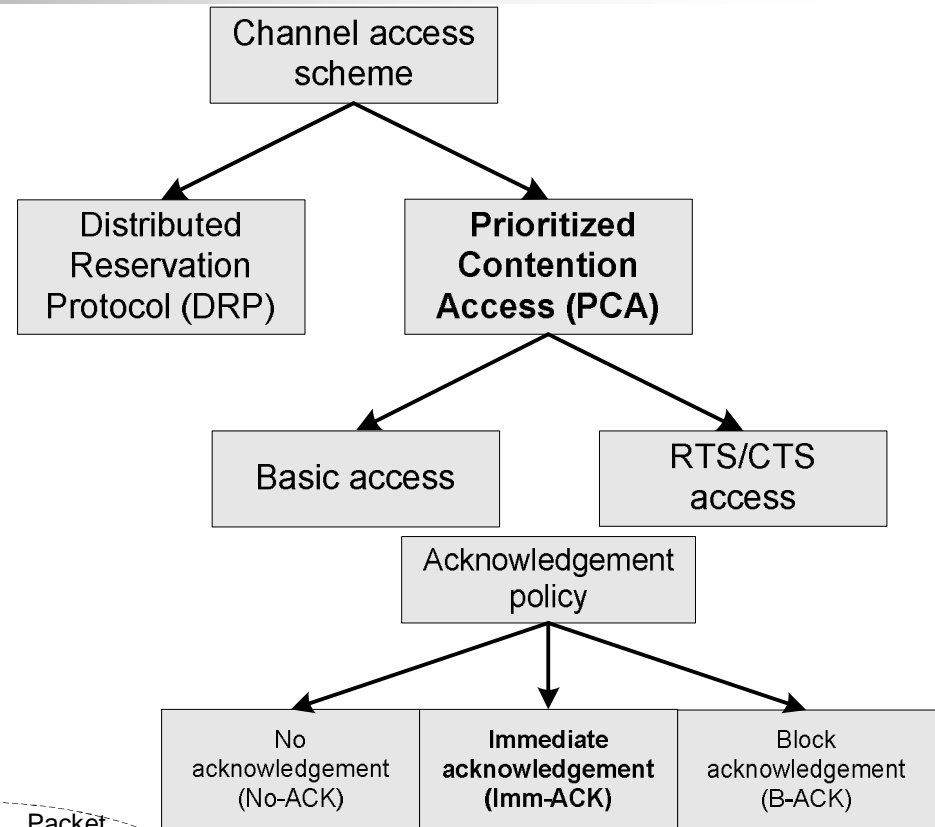
- n Binary Exponential Backoff (BEB) algorithm
- n Base station broadcasts BEB parameters



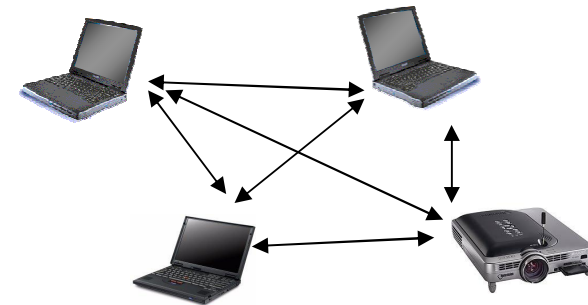
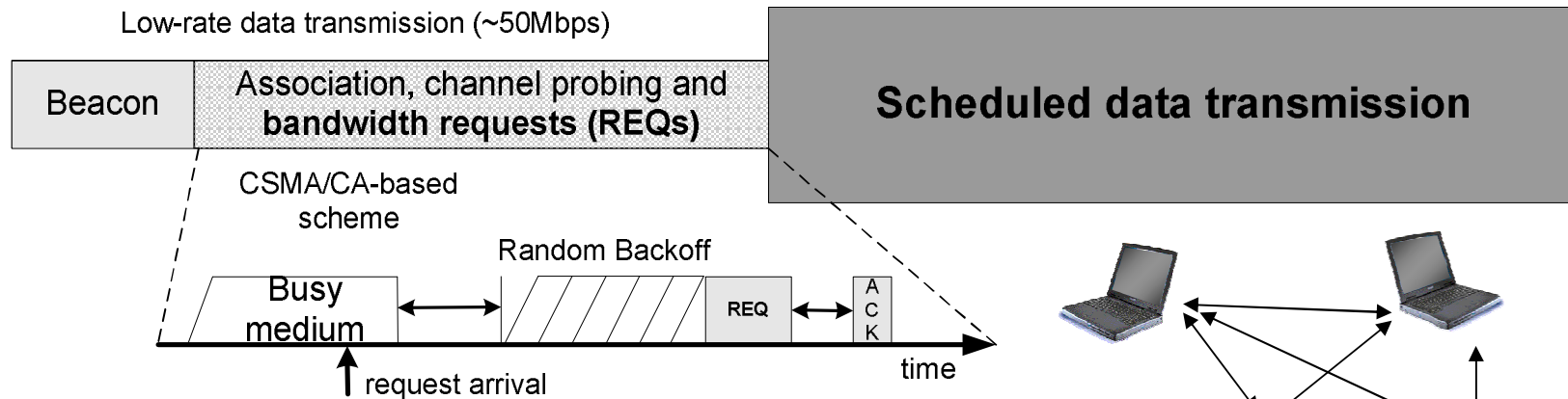
# RMA Applications: ISO/IEC 26907 PAN

## Main features

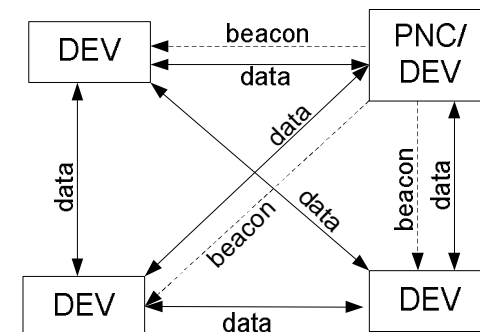
- n Synchronous system
- n Each user broadcasts its beacon
- n Supports both RMA (PCA) and scheduling (DCF)
- n PCA is a CSMA/CA-scheme with QoS support
- n Several ACK policies implemented



# RMA Applications: IEEE 802.15.3c PAN



- n Piconet coordinator (PNC) sends its beacon in each superframe
- n Bandwidth requesting is CSMA/CA-based (low data rates)
- n Data transmission is TDMA-based (high data rates)



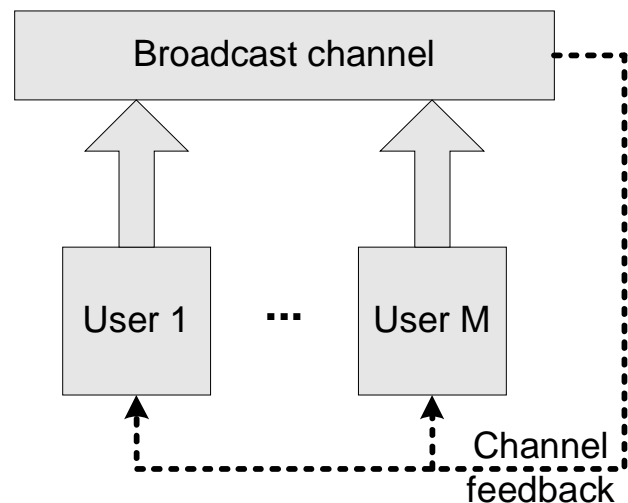


# Reference model of a random multiple access (RMA) system

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# Reference RMA Model

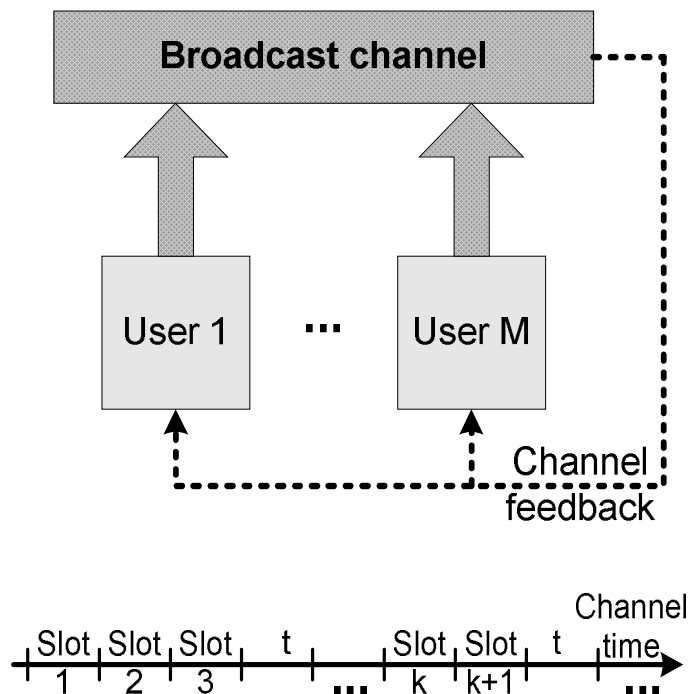
- n Developed in late 70s  
by R. Gallager: "A perspective on multiaccess channels", 1985  
and B. Tsybakov: "Survey of USSR contributions to random multiple-access communications", 1985
- n Discussed by D. Bertsekas and R. Gallager: "Data Networks", 1987



## Principal assumptions:

- A1: Slotted (synchronous) system
- A2: Collision or perfect reception
- A3: Ternary channel feedback
- A4: Immediate channel feedback
- A5: Noise-free channel
- A6: Input source probabilistic model

# A1: Slotted Access



Principal assumptions:

**A1: Slotted (synchronous) system**

- n Equal packet lengths, Tx time is  $t$
- n Slotted channel time, slot duration is  $t$
- n Slot borders are known
- n Tx starts only on slot borders

**A2: Collision or perfect reception**

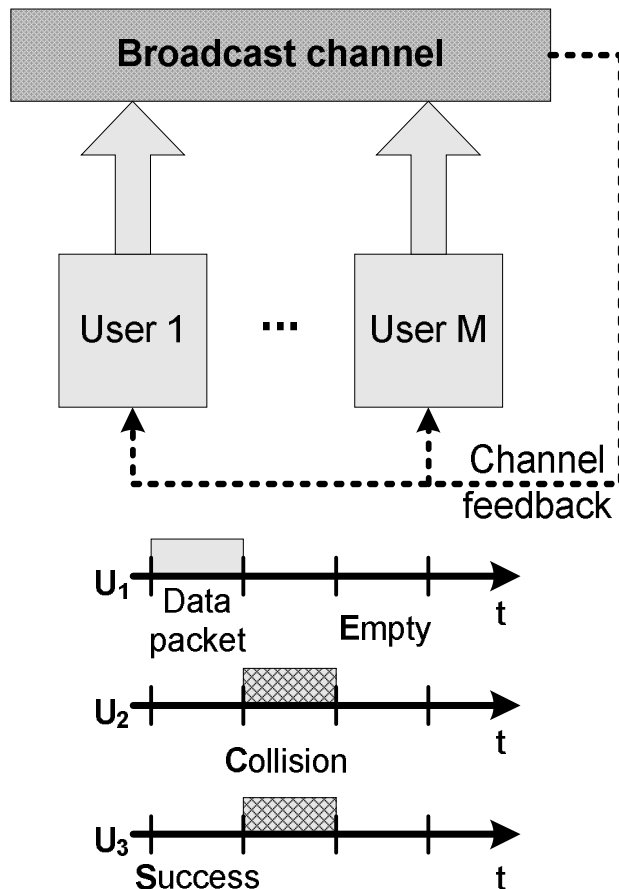
**A3: Ternary channel feedback**

**A4: Immediate channel feedback**

**A5: Noise-free channel**

**A6: Input source probabilistic model**

# A2: Collision or Perfect Reception



Principal assumptions:

A1: Slotted (synchronous) system

A2: Collision or perfect reception

$n$  Define 3 events in broadcast channel:

$n$  1 user Tx per slot → **S**uccess

$n$   $\geq 2$  user Tx per slot → **C**ollision

$n$  0 user Tx per slot → **E**mpy

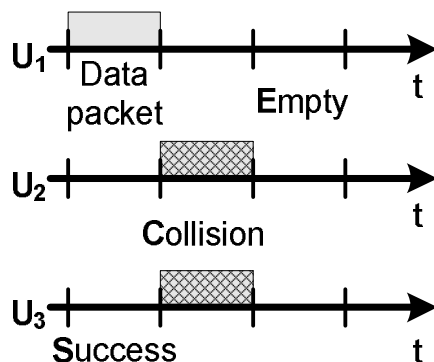
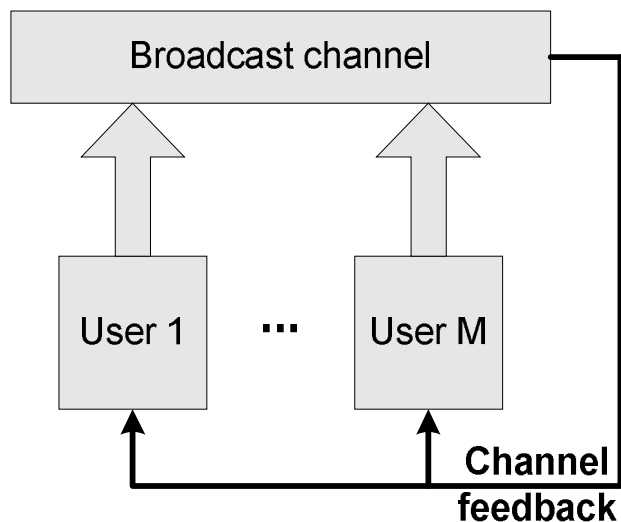
A3: Ternary channel feedback

A4: Immediate channel feedback

A5: Noise-free channel

A6: Input source probabilistic model

# A3: Ternary Channel Feedback



Principal assumptions:

A1: Slotted (synchronous) system

A2: Collision or perfect reception

A3: Ternary channel feedback

$n$  All 3 events are distinguished by a user:

$n$  **S**uccess

$n$  **C**ollision

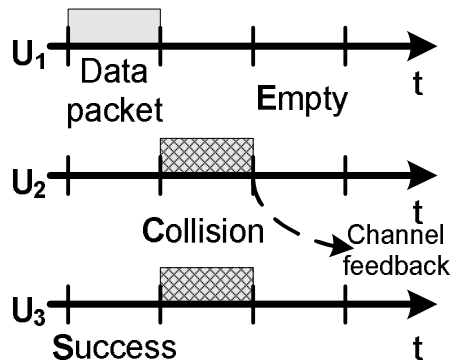
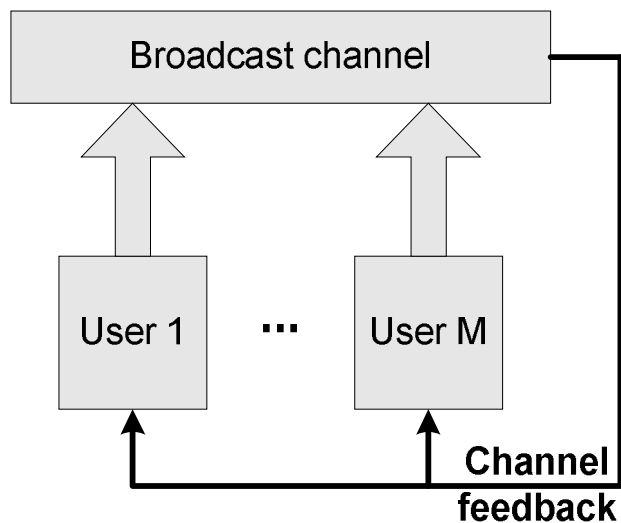
$n$  **E**mpy

A4: Immediate channel feedback

A5: Noise-free channel

A6: Input source probabilistic model

# A4: Fast Channel Feedback



Principal assumptions:

A1: Slotted (synchronous) system

A2: Collision or perfect reception

A3: Ternary channel feedback

**A4: Immediate channel feedback**

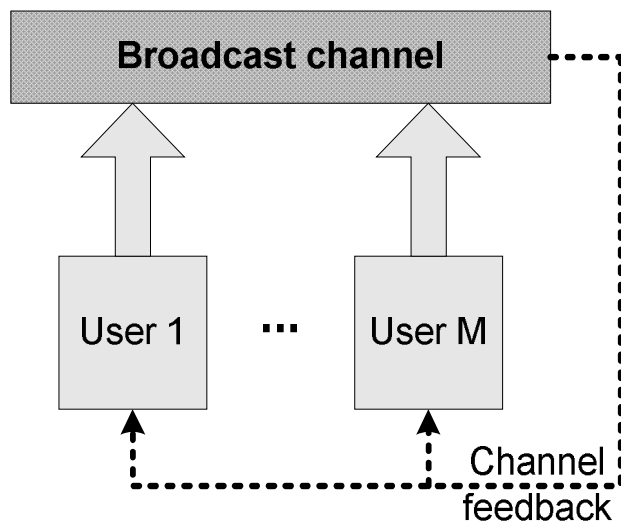
$n$  Current slot event is known by the next slot

A5: Noise-free channel

A6: Input source probabilistic model



# A5: Noise-free Channel



Principal assumptions:

A1: Slotted (synchronous) system

A2: Collision or perfect reception

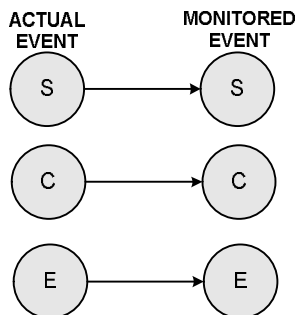
A3: Ternary channel feedback

A4: Immediate channel feedback

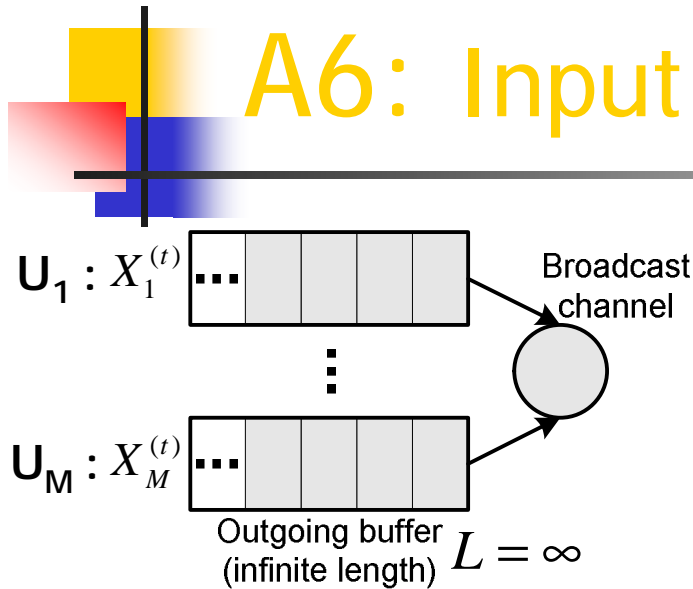
**A5: Noise-free channel**

$n$  Actual channel event coincides with monitored

A6: Input source probabilistic model



# A6: Input Source Probabilistic Model



$M - finite$

$$X_j^{(t)} \in \{0, 1\}, j = \overline{1, M}$$

$$\Pr\{X_j^{(t)} = 1\} = z$$

$$\Pr\{X_j^{(t)} = 0\} = 1 - z$$

$$E\left[\sum_{j=1}^M X_j^{(t)}\right] = M \cdot z = I, \text{ arrival intensity}$$

$$\Pr\left\{\sum_{j=1}^M X_j^{(t)} = i\right\} = \binom{M}{i} \cdot z^i \cdot (1 - z)^{M-i}$$

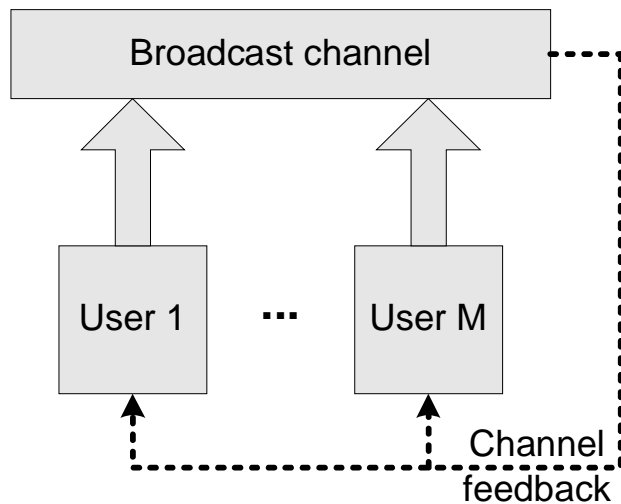
Finite population model with Bernoulli input source  $M < \infty$ . Parameters:  $I, M$

$$\left\{ \begin{array}{l} M \rightarrow \infty \\ z \rightarrow 0 \\ M \cdot z = const = I \end{array} \right. \quad \Pr\left\{\sum_{j=1}^M X_j^{(t)} = i\right\} \rightarrow \frac{I^i}{i!} \cdot e^{-I}$$

User = packet

Infinite population model with Poisson input source  $M = \infty$ . Parameter:  $I$

# Reference RMA Model Summary



Principal assumptions:

A1: Slotted (synchronous) system

A2: Collision or perfect reception

A3: Ternary channel feedback

n Success, Collision, Empty

A4: Immediate channel feedback

A5: Noise-free channel

A6: Input source probabilistic model

n Finite population, Bernoulli source

n Infinite population, Poisson source



# Instability of the RMA algorithms in the existing telecommunication systems

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# RMA Algorithm Definition

RMA algorithm is a rule, according to which a user decides whether to transmit a packet in each slot by monitoring the channel activity

Principal performance characteristics:

n Mean packet delay  $d_a$  of an algorithm

n Enumerate arriving packets

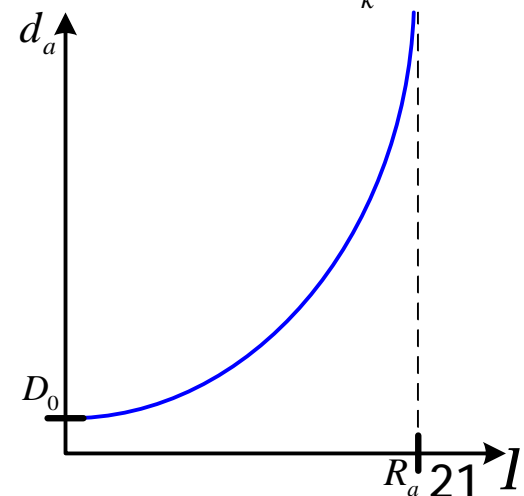
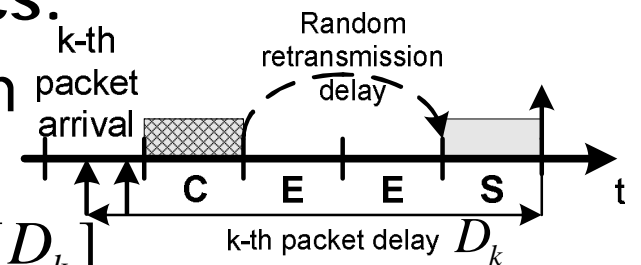
n In stationary conditions:  $d_a = \limsup_{k \rightarrow \infty} E[D_k]$

n Algorithm rate  $R_a$

$$R_a = \sup\{I : d_a(I) < \infty\}$$

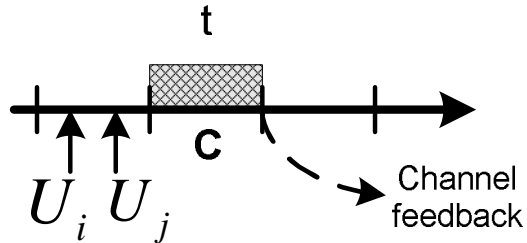
n Capacity  $C_{RMA}^I$  is the upper bound on  $R_a$  for all RMA algorithms  $A$

$$C_{RMA} = \sup_{a \in A} R_a$$



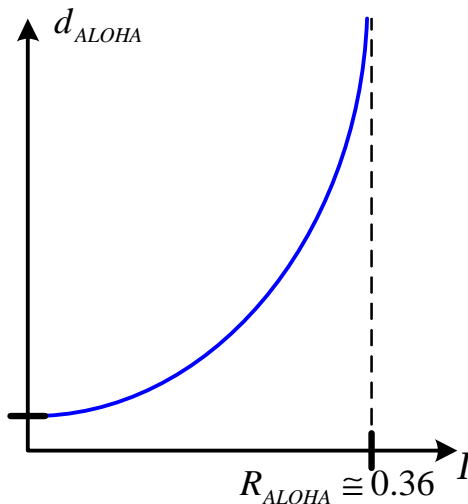
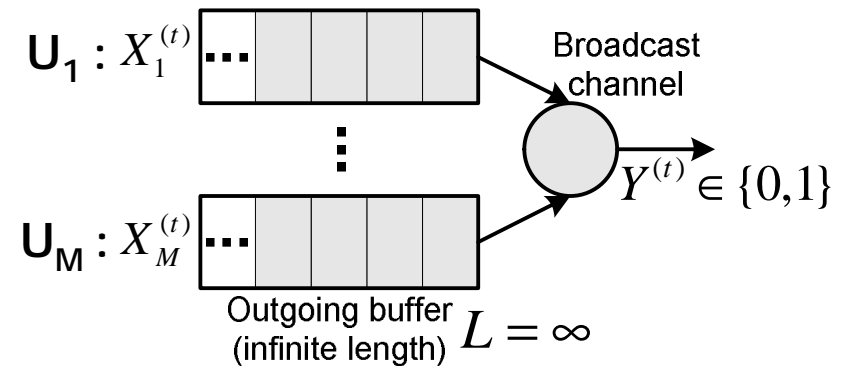
# Finite Population Slotted ALOHA

n Finite population, Bernoulli source:  $M < \infty$



Tx with independent probability  $p$  in each slot after C

Assume saturation conditions:



Stability requirement:  $E[\sum_{j=1}^M X_j^{(t)}] < E[Y^{(t)}]$

$$M \cdot z = 1 < \Pr\{\text{Success\_in\_slot\_t}\} = \binom{M}{1} \cdot p \cdot (1-p)^{M-1} = f(p, M)$$

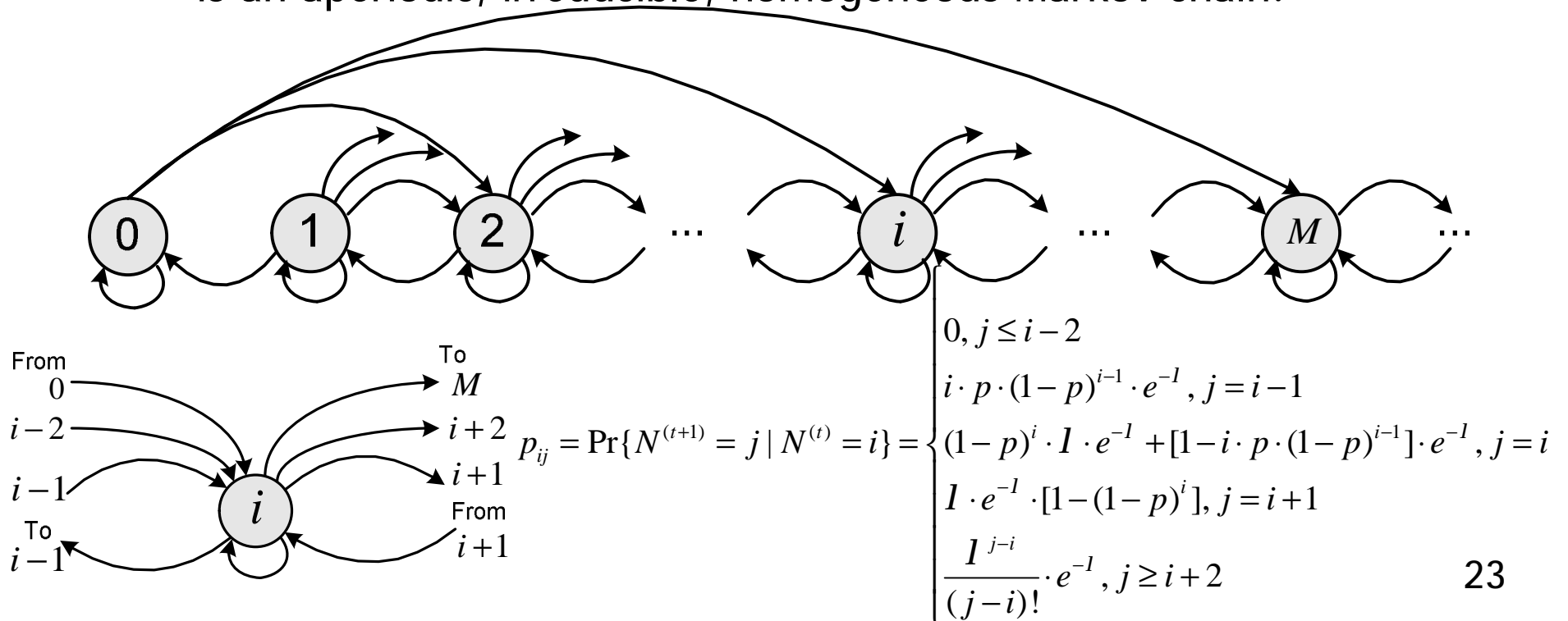
$$\max_p f(p, M) = \left(1 - \frac{1}{M}\right)^{M-1} \cong \frac{1}{e} \quad \text{for } p = \frac{1}{M}$$

# Infinite Population Slotted ALOHA

n Infinite population, Poisson source:  $M = \infty$

$N^{(t)}$  is the number of backlogged users in t-th time slot,

$N^{(t)}$  is an aperiodic, irreducible, homogeneous Markov chain:



# Slotted ALOHA Instability

n Infinite population, Poisson source:  $M = \infty$   
(contd.)

$\forall I > 0$ : Markov chain  $N^{(t)}$  is not stable

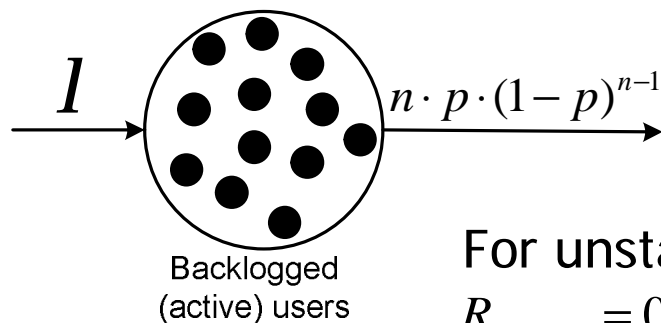
Sufficient to show that  $\exists d > 0, N > 0 : \forall n > N$

$$E[(N^{(t+1)} - n) | N^{(t)} = n] > d$$

$$1 - \Pr\{\text{Success in slot } t | N^{(t)} = n\} = 1 - n \cdot p \cdot (1-p)^{n-1}$$

$$\text{For } n \rightarrow \infty \quad n \cdot p \cdot (1-p)^{n-1} \rightarrow 0$$

System is 'jammed' with collisions for any  $I > 0$



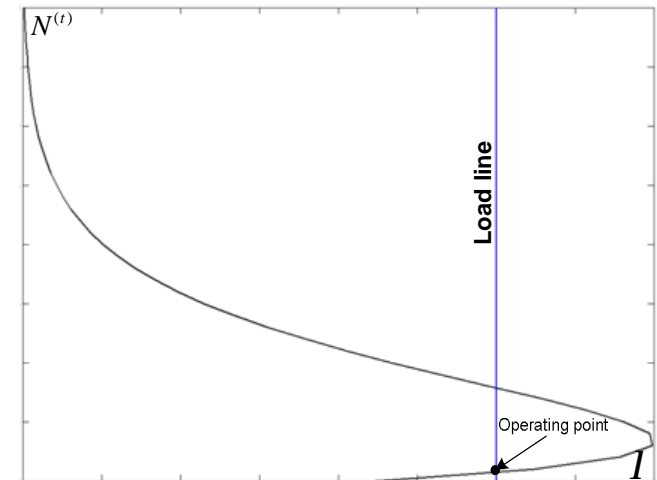
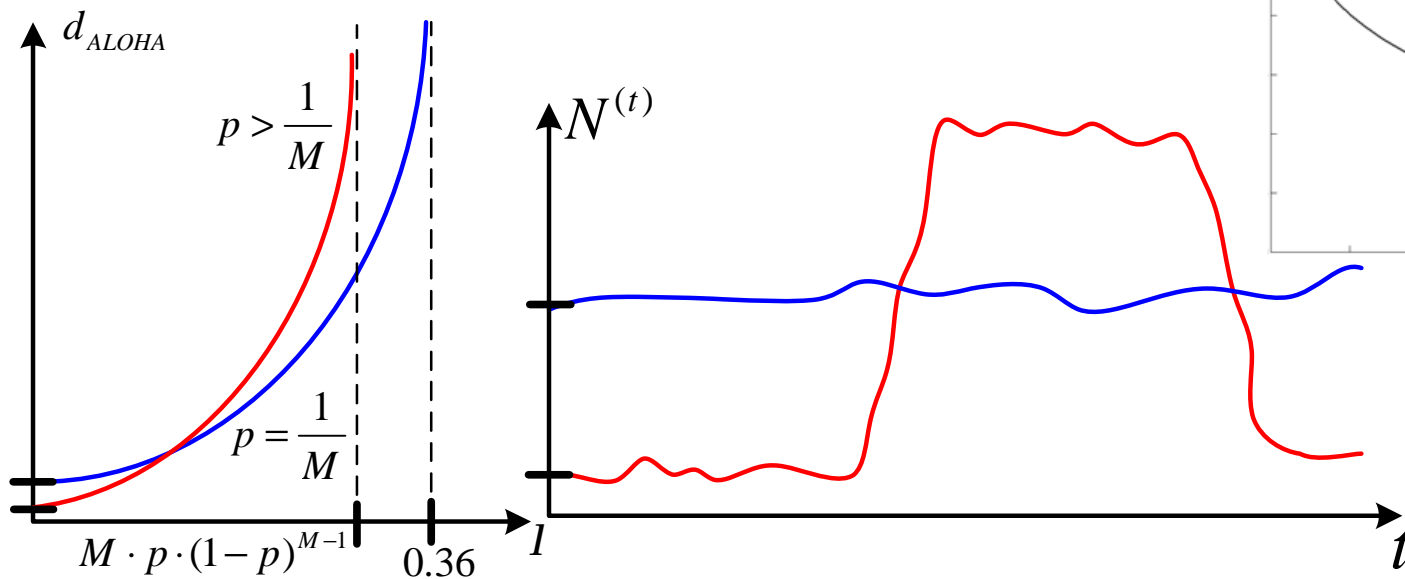
For unstable system packet delay is unbounded!

$$R_{ALOHA} = 0$$



# Slotted ALOHA Summary

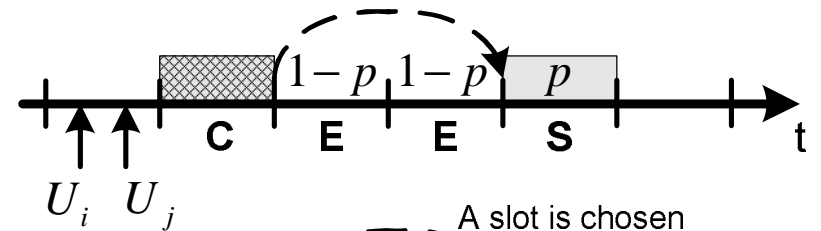
- n For  $M = \infty$  ALOHA is unstable  $\rightarrow R_{ALOHA} = 0$
- n For  $M < \infty$  ALOHA is stable  $\rightarrow R_{ALOHA} \cong 0.36$
- n For large  $M$  ALOHA is bistable:



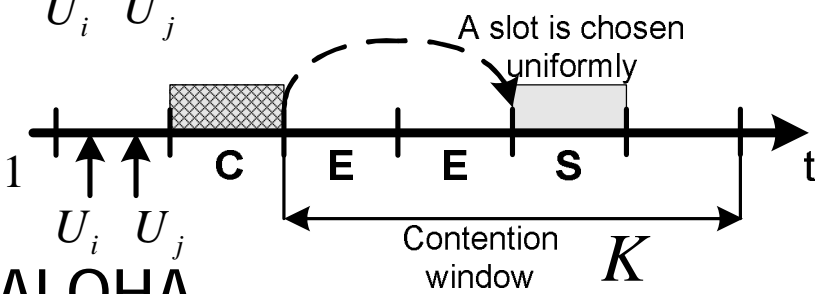
# Binary Exponential Backoff Algorithm

- n Binary Exponential Backoff (BEB) Algorithm is a retransmission control procedure to stabilize ALOHA system
- n It 'accounts' for channel condition
- n Consider 2 variations of slotted ALOHA

- n Geometrical randomization  
Tx with independent probability  $p$  in each slot after C



- n Uniform randomization  
Use contention window of size  $K = \frac{2}{p} - 1$



- n BEB is adaptive uniform slotted ALOHA

Initialization and after each Success  $K_0 = K_{\min}$

After  $i$ -th packet Collision  $K_i = \min(2^i \cdot K_0, K_{\max})$

# BEB Instability

n For  $M = \infty$  BEB is unstable  $\rightarrow R_{BEB} = 0$

Shown by D. Aldous: "Ultimate Instability of Exponential Back-Off Protocol ...", 1987

n For  $M < \infty$  BEB is stable  $\rightarrow R_{BEB} = \frac{1}{2} \cdot \ln 2 \cong 0.346$

Shown by N.-O. Song, B.-J. Kwak, L. Miller: "On the Stability of Exponential Backoff", 2003

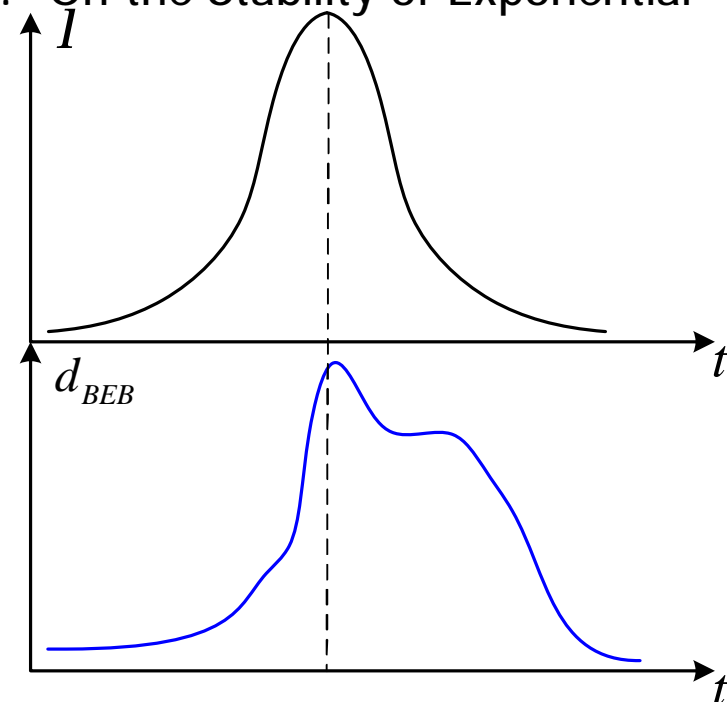
n For large  $M$  BEB is stable but very 'slow' to cope with arrival intensity  $I$  peaks

## Research targets

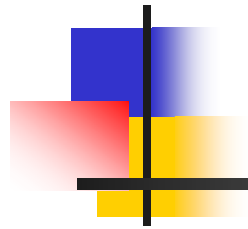
n Achieve  $R_a > R_{ALOHA} > R_{BEB}$

n Combat instability effect

n Ensure fast  $d_a$  reaction



# Tree RMA algorithms as a possible solution for the instability problem



# Contention Tree (CT) Algorithm

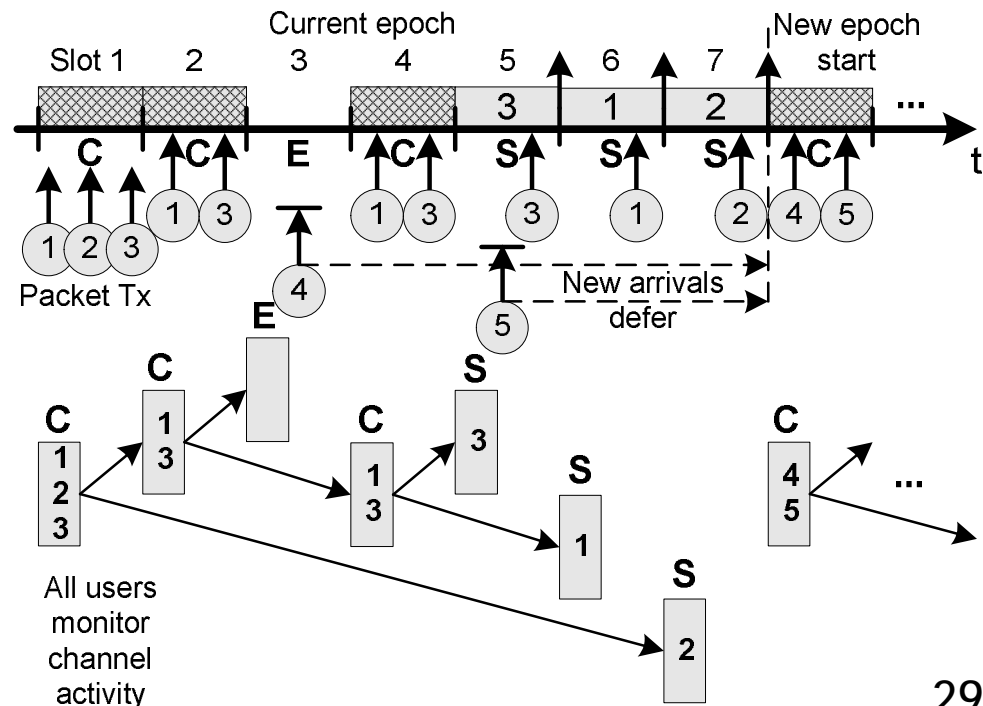
Introduced by

B. Tsybakov, V. Mikhailov: "Slotted multiaccess packet-broadcasting feedback channel", 1978

J. Capetanakis: "Tree algorithms for packet broadcast channels", 1979

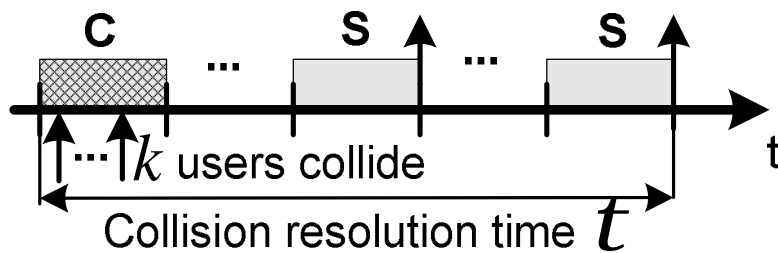
## Main features

- n Random retransmission attempts for conflicting users
- n Newly backlogged users defer Tx until current epoch is finished (blocked channel access)



# CT Stability Analysis

- n Infinite population, Poisson source:  $M = \infty$
- n Define average conflict resolution time:



$$T_k = E[t \mid (k \text{ _collided_ users})]$$

Stability requirement:  $I \cdot E[t] < k \rightarrow I < \frac{k}{T_k}$

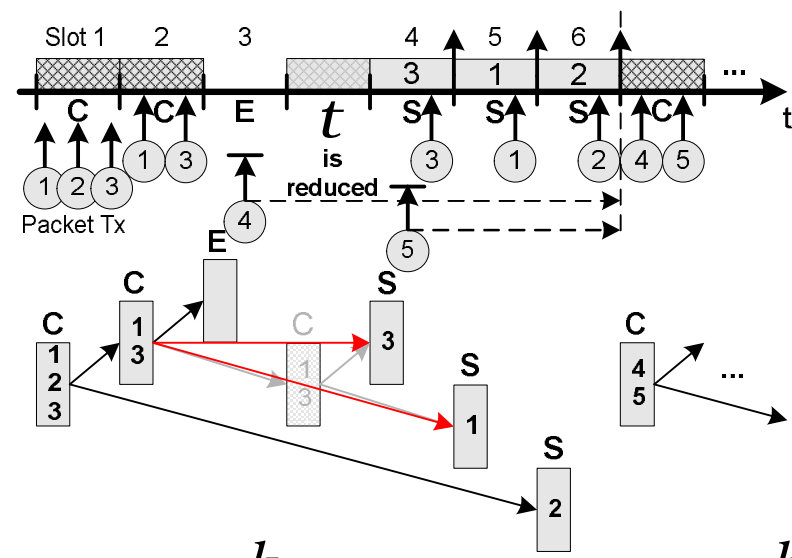
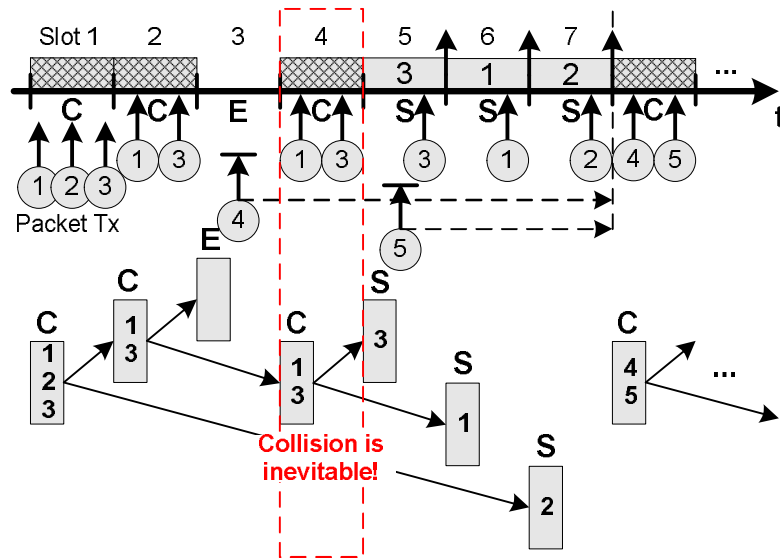
Last known bounds according to  
L. Györfi, S. Györi, J. Massey  
"Principles of Stability Analysis for  
Random Accessing with Feedback", 2007 are

$$\liminf_{k \rightarrow \infty} \frac{k}{T_k} < R_{CT} < \limsup_{k \rightarrow \infty} \frac{k}{T_k}$$

$0.34657320 < R_{CT} < 0.34657397$

Shown that  $R_{CT} \cong \frac{1}{2} \cdot \ln 2 \cong 0.346$  which equals to  $R_{BEB} \cong 0.346$  for  $M < \infty$  30

# Frugal Contention Tree (FCT) Algorithm



Analogously, algorithm rate is bounded by

$$\liminf_{k \rightarrow \infty} \frac{k}{T_k} < R_{FCT} < \limsup_{k \rightarrow \infty} \frac{k}{T_k}$$

Last known bounds according to  
L. Györfi, S. Györi, J. Massey  
"Principles of Stability Analysis for  
Random Accessing with Feedback", 2007 are

$$R_{FCT} \cong \left( \frac{3}{2 \cdot \ln 2} + \frac{1}{2} \right)^{-1} \cong 0.375$$

$$0.3753690 < R_{FCT} < 0.3753698$$

# Blocked and Free Channel Access

- CT and FCT operation may be interpreted as packet PUSH/POP in a virtual stack (only 2 variables are used)

Let  $L^{(t)}$  be the number of packets in the stack

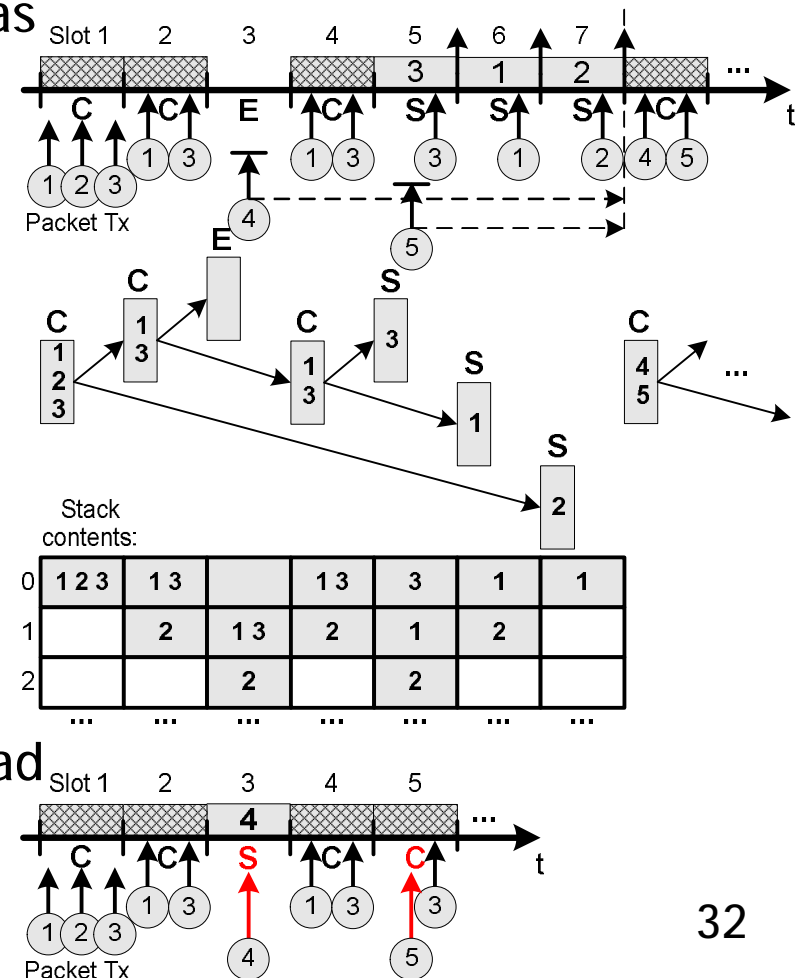
$L^{(t)} = 1$  in the first epoch slot and

$$L^{(t+1)} = \begin{cases} L^{(t)} + 1 & \text{in case of a Collision} \\ L^{(t)} - 1 & \text{otherwise} \end{cases}$$

User should also keep track of its packet number in the stack

- Blocked access rule **complicates implementation** → use free access instead

1 variable is enough to implement the free channel access algorithm





# CT vs. BEB Comparison

n For  $M = \infty$  BEB is unstable  $\rightarrow R_{BEB} = 0$

Shown by D. Aldous: "Ultimate Instability of Exponential Back-Off Protocol ...", 1987

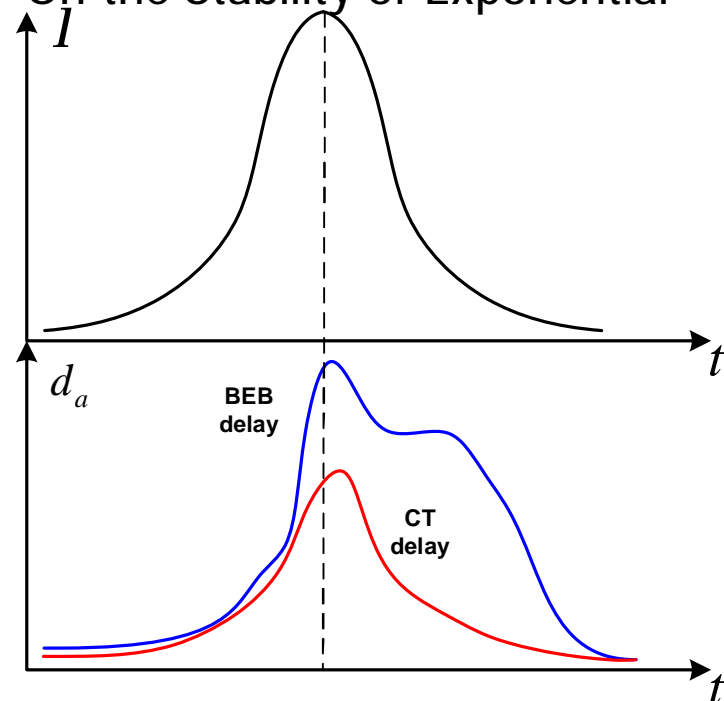
n For  $M < \infty$  BEB is stable  $\rightarrow R_{BEB} = \frac{1}{2} \cdot \ln 2 \cong 0.346$

Shown by N.-O. Song, B.-J. Kwak, L. Miller: "On the Stability of Exponential Backoff", 2003

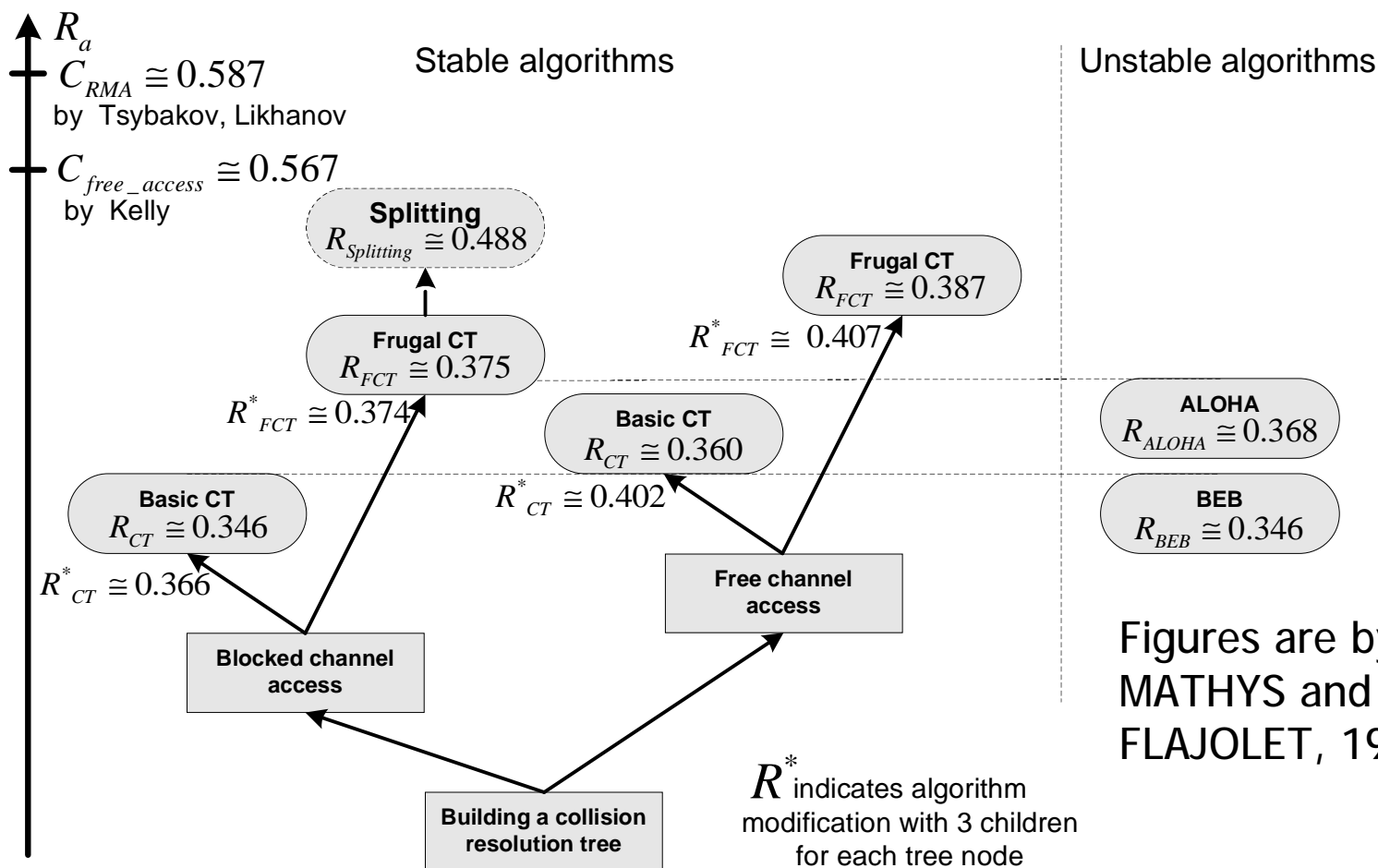
n All CT modifications are stable even for  $M = \infty$

$$R_{CT} \cong \frac{1}{2} \cdot \ln 2 \cong 0.346$$

$$R_{FCT} \cong \left( \frac{3}{2 \cdot \ln 2} + \frac{1}{2} \right)^{-1} \cong 0.375$$

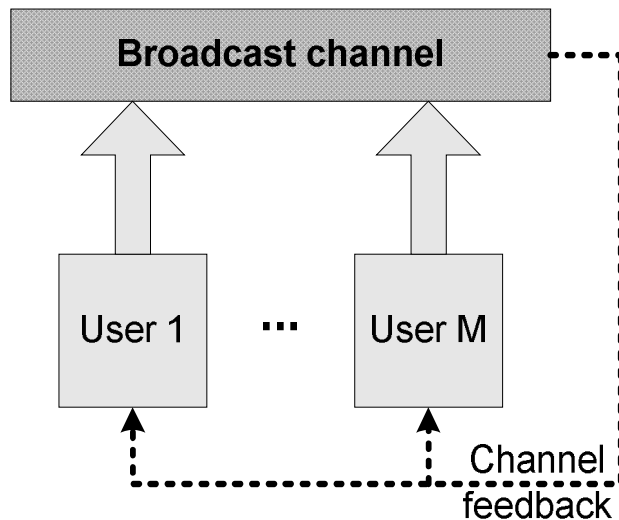


# General RMA Algorithms Comparison



Figures are by PETER MATHYS and PHILIPPE FLAJOLET, 1985

# A5: Noisy Channel Conditions



Principal assumptions:

A1: Slotted (synchronous) system

A2: Collision or perfect reception

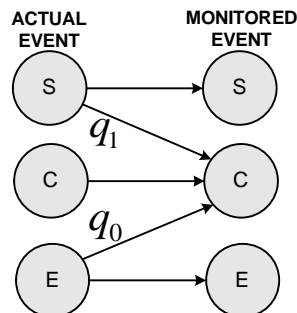
A3: Ternary channel feedback

A4: Immediate channel feedback

**A5: Noisy channel**

n A model with 'false conflicts' by G. Evseev, N. Ermolaev, 1982

A6: Input source probabilistic model



# CT for Noisy Channel (CTN) Performance

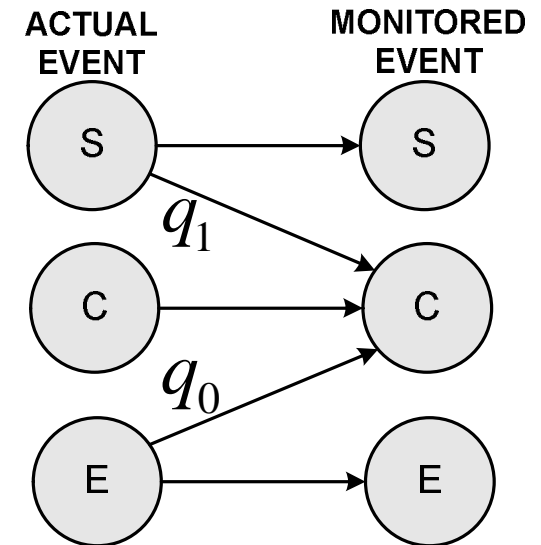
n CT is shown\* to be **stable** for

$$\begin{cases} q_0 < 0.5 \\ q_1 < 1 \end{cases}$$

n FCT is shown\* to be **unstable** for  $q_0 > 0$

$$R_{CTN} \cong \frac{1 - 2 \cdot q_0}{1 - q_0} \cdot \left( \frac{2}{\ln 2} + \frac{2 \cdot (q_1 - q_0)}{(1 - q_1) \cdot (1 - q_0)} \right)$$

n A modification of CT was introduced\*\* ,  
which is **stable** for  $q_0 < 1$



\* G. Evseev, N. Ermolaev "Performance Evaluation of the Collision Resolution for a Random-Access Noisy Channel", 1982

\*\* G. Evseev, A. Turlikov "Throughput Analysis for a Noise-Resistant Multiple Access Algorithm", 1986

# CT Algorithms Summary

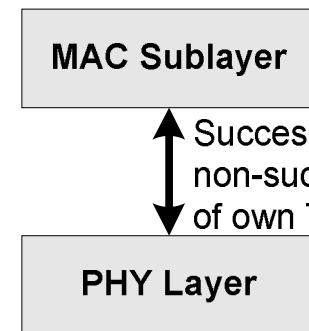
## Benefits

- n Higher rate than that of BEB algorithm
- n Lower packet **delay** than that of BEB algorithm
- n **Stability** for high user population
- n **Easy implementation**

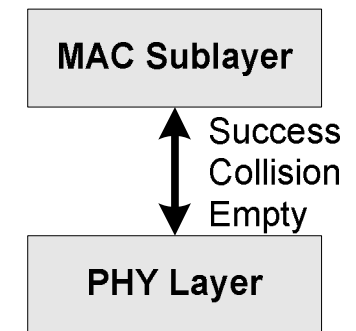
## Open problems

- n Extended PHY-MAC interface is required or **stabilization technique\*** for Success Non-Success feedback


Available information



Required information



\* partially resolved in A. Malkov, A. Turlikov "Random-Multiple Access Protocols for communication Systems with "Success – Failure" Feedback", 1995



# Tree algorithms implementation issues and alternative proposals

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# Research Directions

## n By intervention level

n Analysis/optimization of existing systems (□)

n Novel approaches and algorithms (□)

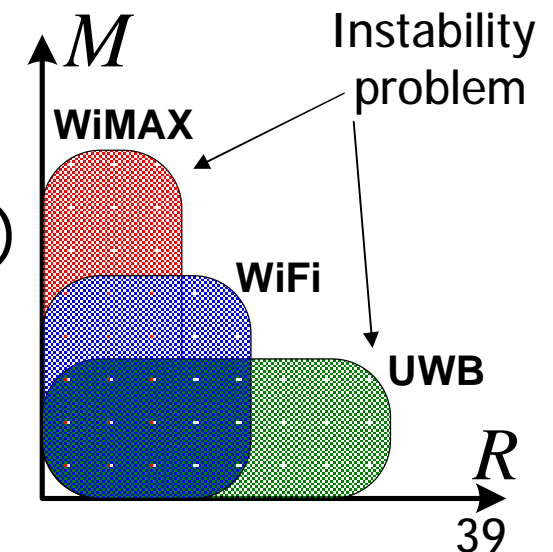
n Supportive activity (□)

## n By system under consideration

n PAN: IEEE 802.15.3c, ISO 26907 (UWB)

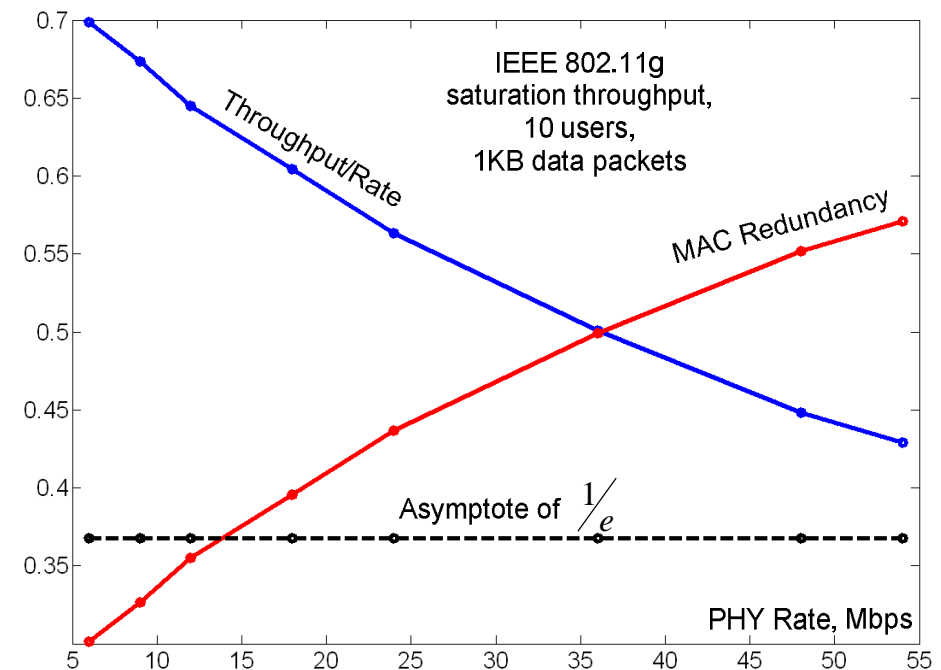
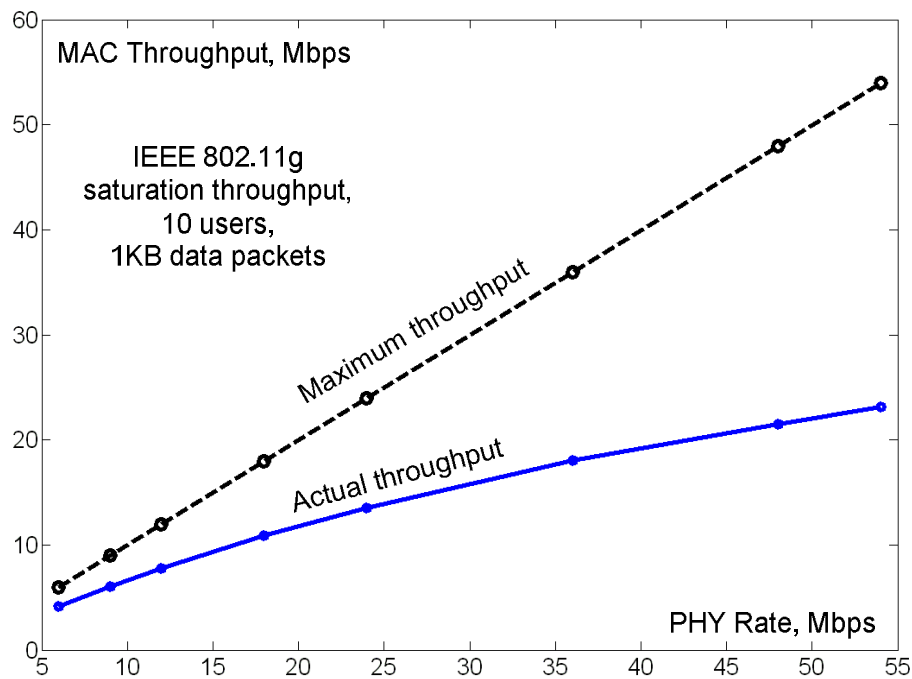
n LAN: IEEE 802.11 (WiFi)

n WAN: IEEE 802.16 (WiMAX)



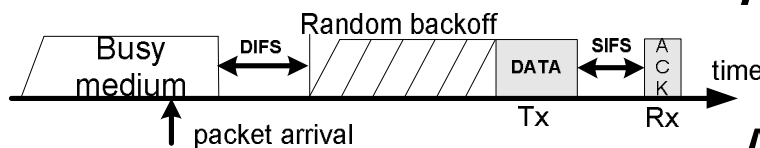
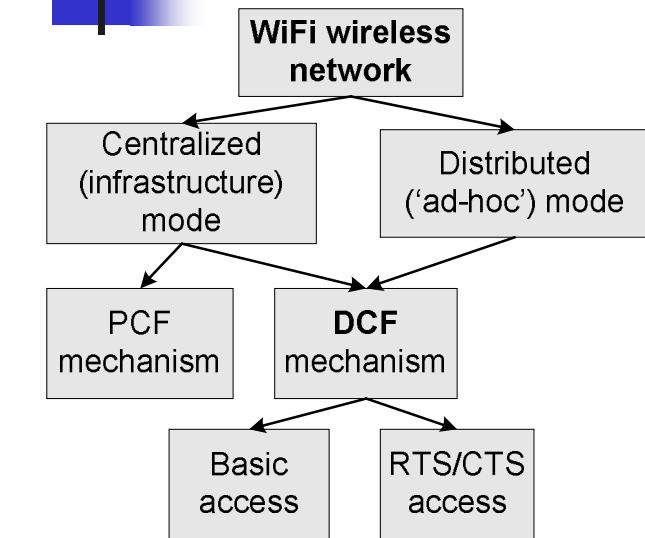
# Open Problems: IEEE 802.11 LAN

- n Follow Bianchi approach to calculate throughput in saturation conditions
- n Gap between PHY rate and MAC SAP throughput increases as rate grows
- n With user population or data rate increase a system will show instability





# Reference Model: IEEE 802.11 LAN



## Principal assumptions:

### A1: Unequally-slotted system

- n Success = DATA + SIFS + ACK + DIFS
- n Conflict = DATA + EIFS
- n Empty = aSlotTime

### A2: Collision or perfect reception

### A3: Binary channel feedback

- n Success, Non-success

### A4: Immediate channel feedback

### A5: Noise-free or Noisy channel

### A6: Input source probabilistic model



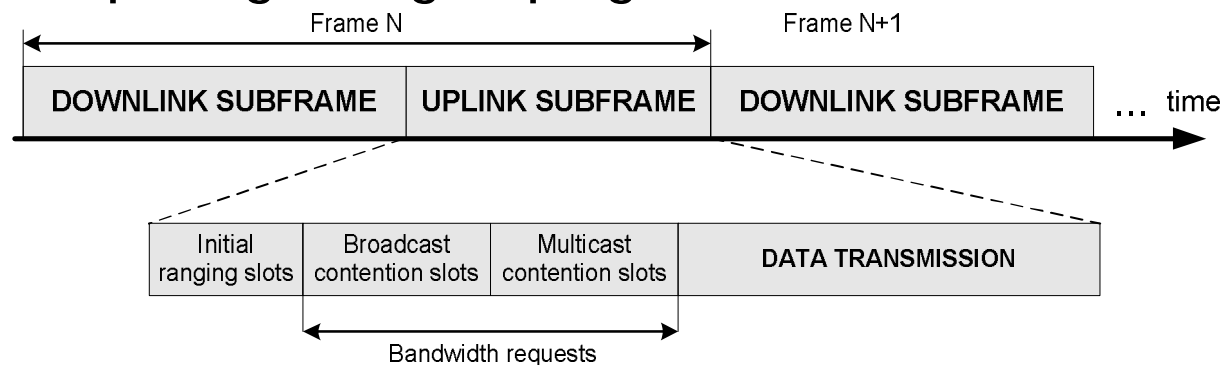
# IEEE 802.11 Research Directions

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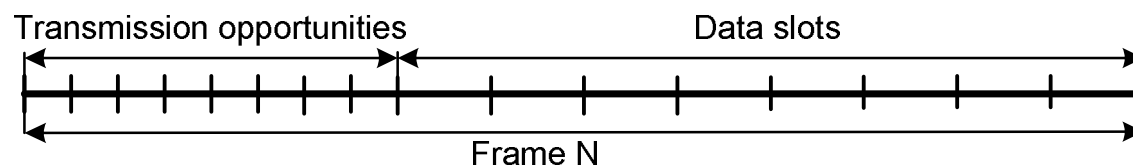
- n Analytical model for mean delay analysis
- n New standards simulation (.11e and .11n)
- n High-precision throughput measurement
- n Experimental wireless channel model
- n BEB optimization proposal
- n Performance enhancement for noisy channel (NACK)
- n Tree algorithm consideration

# Open Problems: IEEE 802.16 WAN

- n Optimal bandwidth reservation scheme
  - n Broadcast polling
  - n Multicast polling and grouping



- n Performance optimization and stability enforcement
  - n Optimal Polling slots / Data slots separation



# Reference Model: IEEE 802.16 WAN

BEB is used to resolve bandwidth request collisions

Principal assumptions:

A1: Slotted (synchronous) system

A2: Collision or perfect reception

A3: Binary channel feedback

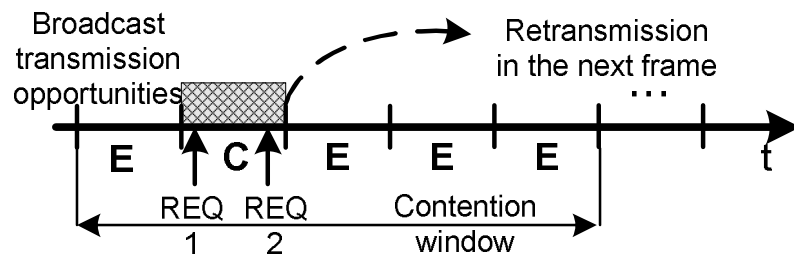
$n$  Success, Non-success

A4: Delayed channel feedback

$n$  Feedback available by the next frame

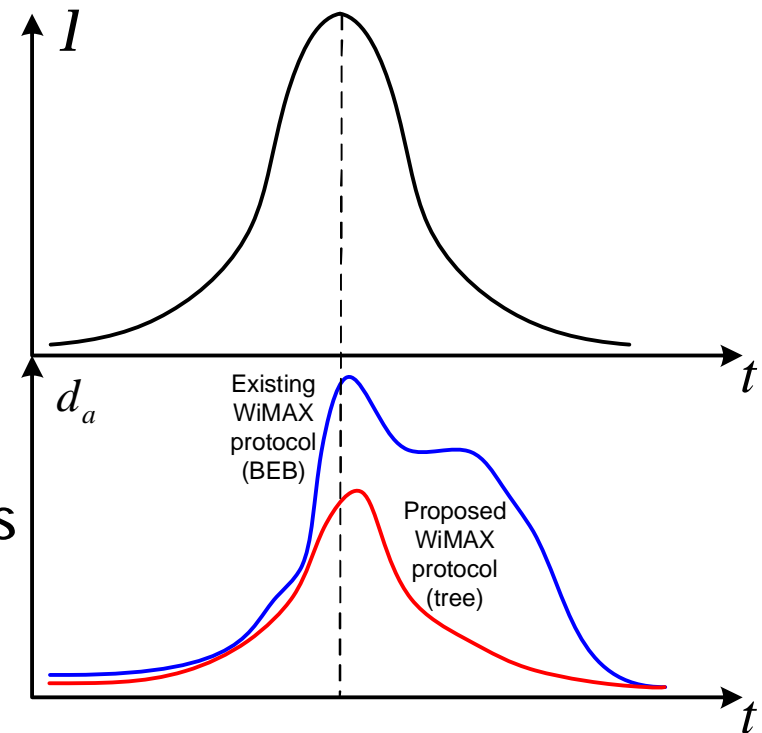
A5: Noise-free channel

A6: Input source probabilistic model

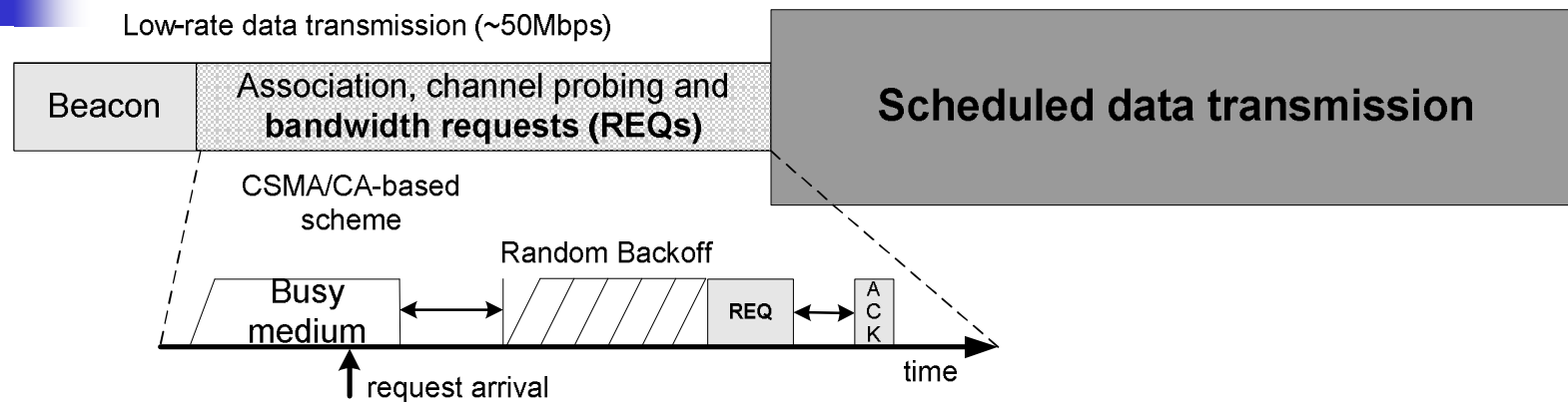


# IEEE 802.16 Research Directions

- n Broadcast polling mechanism analysis
- n Multicast polling mechanism analysis
- n User grouping for different QoS criteria
- n Performance optimization, optimal Polling slots / Data slots separation  
(A. Turlikov, A. Vinel "Capacity Estimation of Centralized Reservation-Based Random Multiple-Access System", 2007)
- n MAC protocol replacement considerations  
(V. Kobliakov, A. Turlikov, A. Vinel "Distributed Queue Random Multiple Access Algorithm for Centralized Data Networks", 2006)
- n MAC protocols stability research

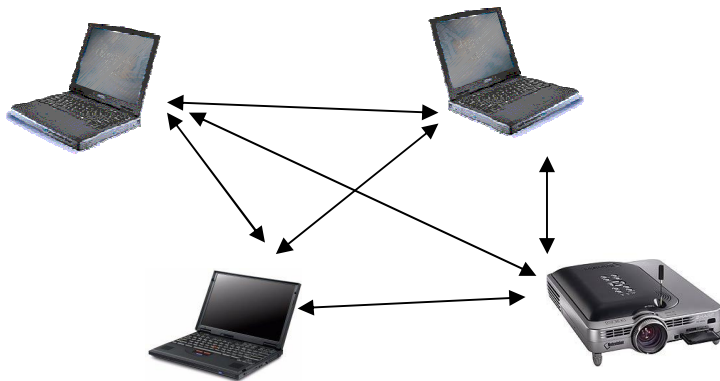


# Open Problems: IEEE 802.15.3c PAN



- n **Low-rate data transmission time should be minimized (protocol overhead)**
- n **Instability problem may arise due to saturation conditions**
- n **Packet delay for request Tx should be minimized**

# Reference Model: IEEE 802.15.3c PAN



Principal assumptions:

**A1: Unequally-slotted system**

- n Success = *undefined*
- n Conflict = *undefined*
- n Empty = *undefined*

**A2: Collision or perfect reception**

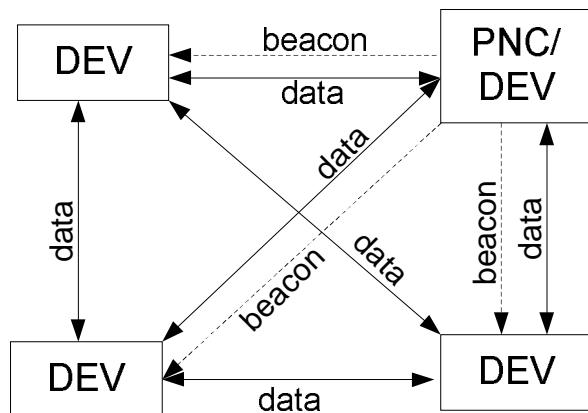
**A3: Binary channel feedback**

- n Success, Non-success

**A4: Immediate channel feedback**

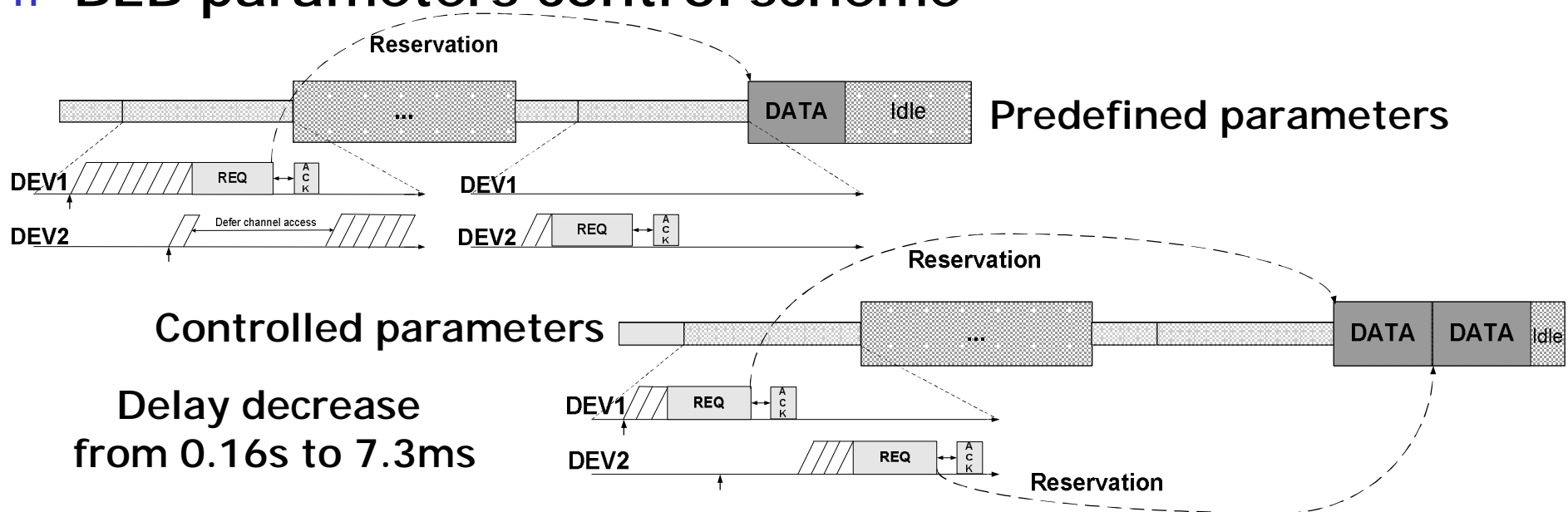
**A5: Noise-free or Noisy channel**

**A6: Input source probabilistic model**



# IEEE 802.15.3c Research Directions

- n Performance enhancement for noisy channel (NACK)\*
- n BEB parameters control scheme



- n Tree algorithm consideration

\* S. Andreev, A. Vinel "Performance Analysis and Enhancement of an Ultra-Wideband WPAN MAC in the Presence of Noise", 2007





# Multiple Access Group Achievements

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## n Research

- n Analytical models of MAC operation are built (UWB, WiFi, WiMAX)
- n Performance of standard MAC protocols is optimized (UWB, WiMAX)
- n Alternative protocols are considered (WiMAX)
- n 12 scientific publications during 2007

## n Education

- n 2 lecture courses on the subject
- n 2 PhD dissertations defended in 2006, 1 in 2007



# Discussion

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